

Recall from lecture:

$$\underline{f}_{i+1/2}^{Re} = \frac{1}{2} (\underline{f}_i + \underline{f}_{i+1}) - \frac{1}{2} \underline{|A|} (\underline{Q}_{i+1} - \underline{Q}_i) \quad (*)$$

$$\underline{Q}_i^{n+1} = \underline{Q}_i^n - \frac{\Delta t}{\Delta x} \left( \underline{f}_{i+1/2}^{Re} - \underline{f}_{i-1/2}^{Re} \right)$$

Why can't we apply this yet for non-conservative systems?

→ We are given

$$\frac{\partial Q}{\partial t} + \underline{A(Q)} \frac{\partial Q}{\partial x} = 0$$

without the ability to transform

$$\underline{A(Q)} \frac{\partial Q}{\partial x} = \frac{\partial f}{\partial Q} \frac{\partial Q}{\partial x} = \frac{\partial f}{\partial x}$$

into  $\underline{A(Q)} = \frac{\partial f}{\partial Q} + \underline{NC}$

How to proceed:

$$\text{Add a "0": } 0 = \underline{f}_i - \underline{f}_i$$

$$\Rightarrow \underline{Q}_i^{n+1} = \underline{Q}_i^n - \frac{\Delta t}{\Delta x} \left( \underbrace{f_{i+1/2}^{Roe}}_{(A)} - \underline{f}_i + \underline{f}_i - \underbrace{f_{i-1/2}^{Roe}}_{(B)} \right)$$

(A) Plug in (x)

$$(A) = \left( \frac{1}{2} (\underline{h}_{i+1} + \underline{h}_i) - \frac{1}{2} |\underline{A}| (\underline{Q}_{i+1} - \underline{Q}_i) \right) - \underline{f}_i$$

$$= \frac{1}{2} (\underline{h}_{i+1} - \underline{h}_i) - \frac{1}{2} |\underline{A}| (\underline{Q}_{i+1} - \underline{Q}_i)$$

$$= \frac{1}{2} \underline{A} (\underline{Q}_{i+1} - \underline{Q}_i) - \frac{1}{2} |\underline{A}| (\underline{Q}_{i+1} - \underline{Q}_i)$$

$$(B) = \underline{f}_i - \left( \frac{1}{2} (\underline{h}_i + \underline{h}_{i-1}) - \frac{1}{2} |\underline{A}| (\underline{Q}_i - \underline{Q}_{i-1}) \right)$$

$$= \frac{1}{2} (\underline{h}_i - \underline{h}_{i-1}) + \frac{1}{2} |\underline{A}| (\underline{Q}_i - \underline{Q}_{i-1})$$

$$= \frac{1}{2} \underline{A} (\underline{Q}_i - \underline{Q}_{i-1}) + \frac{1}{2} |\underline{A}| (\underline{Q}_i - \underline{Q}_{i-1})$$

$$\Rightarrow \underline{Q}_{i+1} = \underline{Q}_i - \frac{\Delta t}{\Delta x} \left( \underbrace{p_{i+1/2} - h}_{\text{Fluctuations}} + \underbrace{h_i - h_{i-1/2}}_{\text{Fluctuations}} \right)$$

$$\text{"Fluctuations"} \quad \equiv \underline{D}_{i+1/2}^- + \equiv \underline{D}_{i+1/2}^+$$

Remark: Note the sign  $\nearrow$  which is positive!

$$\underline{D}_{i+1/2}^- := (A) = \frac{1}{2} \underline{A} (\underline{Q}_{i+1} - \underline{Q}_i) - \frac{1}{2} |\underline{A}| (\underline{Q}_{i+1} - \underline{Q}_i)$$

$$\underline{D}_{i+1/2}^+ := (B) = \frac{1}{2} \underline{A} (\underline{Q}_i - \underline{Q}_{i-1}) + \frac{1}{2} |\underline{A}| (\underline{Q}_i - \underline{Q}_{i-1})$$

Code: We require  $\underline{A} = \frac{\partial f}{\partial \underline{Q}} + \underline{N C}$

We require  $|\underline{A}|$ .

if  $\underline{A} = \underline{R} \underline{\Lambda} \underline{R}^{-1}$ , then

$$|\underline{A}| = \underline{R} |\underline{\Lambda}| \underline{R}^{-1}$$

## 2D - quadrilateral FVM?

$$\underline{Q}_i^{n+1} = \underline{Q}_i^n - \left( \underline{g}_{Ni} - \underline{g}_{Si} + \underline{f}_{ei} - \underline{f}_{wi} \right)$$

$\quad \quad \quad + \underline{g}_i \quad \quad \quad - + \underline{f}_i$

For the PDE:

$$\frac{\partial Q}{\partial t} + \underline{A}(\underline{Q}) \frac{\partial Q}{\partial x} + \underline{B}(\underline{Q}) \frac{\partial Q}{\partial y} = 0$$

it follows that

$$\underline{g}_{Ni} - \underline{g}_i \equiv \underline{D}_N^- = \frac{1}{2} \left( \underline{B}(\underline{Q}_N - \underline{Q}_i) - |\underline{B}(\underline{Q}_N - \underline{Q}_i)| \right)$$

$$\underline{g}_i - \underline{g}_{Si} \equiv \underline{D}_S^+ = \frac{1}{2} \left( \underline{B}(\underline{Q}_i - \underline{Q}_S) + |\underline{B}(\underline{Q}_i - \underline{Q}_S)| \right)$$

$$\underline{f}_{e_i - h_i} \equiv \underline{D}_e^- = \frac{1}{2} (\underline{A}(\underline{Q}_e - \underline{Q}_i) - \underline{A}(\underline{Q}_e - \underline{Q}_i))$$

$$\underline{f}_i - \underline{f}_{w_i} = \underline{D}_w^+ = \frac{1}{2} (\underline{A}(\underline{Q}_i - \underline{Q}_w) + \underline{A}(\underline{Q}_i - \underline{Q}_w))$$

Recall :

The matrices  $\underline{A} = \underline{A}(\underline{Q}_i, \underline{Q}_j)$

$$\underline{B} = \underline{B}(\underline{Q}_i, \underline{Q}_j)$$

are defined via the path-integral.

E.g.

$$\underline{A}(\underline{Q}_i, \underline{Q}_j) = \int_0^1 \underline{A}(\underline{\psi}(s)) ds$$

with segment path

$$\underline{\psi}(s) = \underline{Q}_i + s(\underline{Q}_j - \underline{Q}_i)$$

We approximate this integral by  
the most basic integration, the midpoint  
rule.

$$\underline{\underline{A}}(\underline{\underline{a}}_i, \underline{\underline{a}}_j) \approx \underline{\underline{A}}(\psi(0.5))$$

$$= \underline{\underline{A}}\left(\frac{1}{2}(\underline{\underline{a}}_i + \underline{\underline{a}}_j)\right)$$